

# Residual permutation test for high-dimensional regression coefficient testing

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*Joint work with Kaiyue Wen & Tengyao Wang*



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**Our goal:** Test whether

$$H_0 : b = 0 \quad \text{v.s.} \quad H_1 : b \neq 0$$

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  - Usually requires  $p = o(n)$  or some sparsity assumption on  $\beta$ .
  
- Finite-population validity: valid size control with arbitrary  $n$ .

⇒ Our **target of interest**

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- **Distribution-free valid test** (Lei and Bickle, 2021): just requires  $\varepsilon$  to be **exchangeable** for correct size control;
  - **Limitation:** strong assumptions on dimension of  $\mathbf{X}$ :

$$n/p > 1/\alpha + 1$$

↑ **prespecified** Type-I error

$$\alpha = 0.01, n = 300 : p < 3.$$

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when  $\varepsilon_1, \varepsilon_2, \dots$  are independent with uniformly bounded  $(1+t)$ -th order moment for  $t \in [0, 1]$ , our test can have power even when  $b$  is as small as  $n^{-t/(1+t)}$ .

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- Minimax rate optimality:  $n^{-t/(1+t)}$  matches the minimax lower bound rate for coefficient test with heavy-tailed noises.

# Numerical analysis of ANOVA's validity

Simulations for general noise:

$$\mathbf{Y} = \mathbf{X}\beta + \boldsymbol{\varepsilon}$$

$$\mathbf{Z} = \mathbf{X}\beta^Z + \mathbf{e}$$

- $(n, p) = (300, 100), (600, 100), (600, 200)$ ;
- $\mathbf{X}$ : Gaussian design,  $t_1$  design;
- $\mathbf{e}, \boldsymbol{\varepsilon}$ :  $t_1$  noise,  $t_2$  noise, Gaussian noise.

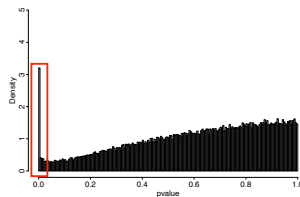


# Validity of ANOVA

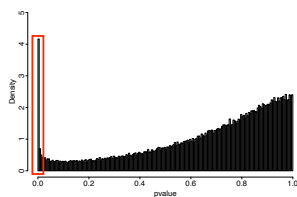
n	p	X type	noise type	0.01	0.005
300	100	Gaussian	Gaussian	0.0101	0.0050
300	100	Gaussian	$t_1$	0.0181	0.0160
300	100	Gaussian	$t_2$	0.0153	0.0107
300	100	$t_1$	Gaussian	0.0101	0.0050
300	100	$t_1$	$t_1$	0.0243	0.0208
300	100	$t_1$	$t_2$	0.0180	0.0130
600	200	Gaussian	Gaussian	0.0101	0.0049
600	200	Gaussian	$t_1$	0.0141	0.0122
600	200	Gaussian	$t_2$	0.0150	0.0104
600	200	$t_1$	Gaussian	0.0101	0.0049
600	200	$t_1$	$t_1$	0.0202	0.0173
600	200	$t_1$	$t_2$	0.0170	0.0120

Table: empirical size with nominal levels  $\alpha = 0.01$  and 0.005

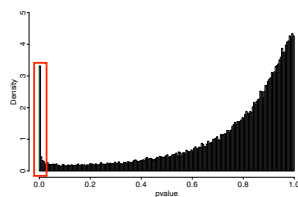
# Histogram of ANOVA's p-values



(a)



(b)



(c)

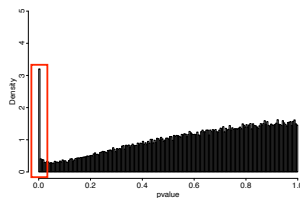
(a)  $n = 300, p = 100$ , Gaussian design,  $t_1$  noises;

(b)  $n = 300, p = 100$ ,  $t_1$  design,  $t_1$  noises;

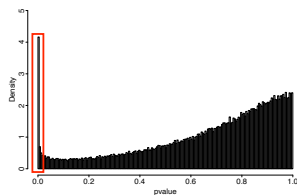
(c)  $n = 600, p = 100$ , Gaussian design,  $t_1$  noises;

$\Rightarrow$  highest spike in heavy-tail design + heavy-tail noise.

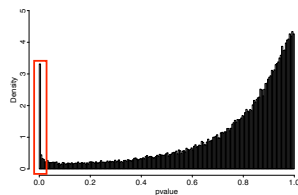
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(d)



(e)



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- (c)  $n = 600, p = 100$ , Gaussian design,  $t_1$  noises;

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This shows the importance of developing a  
**distribution-free & finite-population valid test!!**

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- p-value:

$$\phi = \frac{1}{1+K} \left( 1 + \sum_{k=1}^K \mathbb{1} \left\{ \min_{1 \leq k' \leq K} T(\tilde{\mathbf{V}}_{k'}^T \mathbf{Z}, \tilde{\mathbf{V}}_{k'}^T \mathbf{Y}) \leq T(\tilde{\mathbf{V}}_k^T \mathbf{Z}, \tilde{\mathbf{V}}_k^T \mathbf{P}_k \mathbf{Y}) \right\} \right)$$

$\Rightarrow$  Projecting  $(\mathbf{Y}, \mathbf{P}_k \mathbf{Y})$  onto  $\text{span}(\tilde{\mathbf{V}}_k)$  & compare.

# Why residual permutation test?

- Classical regression residual:

$$\hat{\mathbf{R}}_Y = (\mathbf{I} - \mathbf{X}(\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top) \mathbf{Y}$$

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- $\tilde{\mathbf{V}}_k^\top \mathbf{Y}$ :

↪ a residual by regressing  $\mathbf{Y}$  onto both  $\mathbf{X}$  &  $\mathbf{P}_k \mathbf{X}$  ...

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for some  $g(\cdot)$  depending only on  $\mathbf{X}, \mathbf{Z}, \mathcal{P} := \{\mathbf{P}_0 = \mathbf{I}, \mathbf{P}_1, \dots, \mathbf{P}_K\}$ .



## Remaining challenge:

$$\text{Prove } \phi \geq \frac{1}{1+K} \left( 1 + \sum_{k=1}^K \mathbb{1} \{g(\boldsymbol{\varepsilon}) \leq g(\mathbf{P}_k \boldsymbol{\varepsilon})\} \right) \text{ is a valid p-value (1)}$$

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## Lemma

Suppose we construct  $\mathcal{P} := \{\mathbf{P}_0 := \mathbf{I}, \mathbf{P}_1, \dots, \mathbf{P}_K\}$  s.t. it formalizes a group:

$$\forall \mathbf{P}_i, \mathbf{P}_j \in \mathcal{P}, \exists \mathbf{P}_\ell \text{ s.t. } \mathbf{P}_\ell := \mathbf{P}_i \mathbf{P}_j.$$

Then (1) is a valid p-value.

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- 1 Construction of  $\tilde{\mathbf{V}}_k$  requires  $p < n/2$ ;
- 2 With prespecified  $\alpha$ , one needs to choose  $K > 1/\alpha$  to have power.

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Assume  $\varepsilon_1, \dots, \varepsilon_n \stackrel{i.i.d.}{\sim} \mathbb{P}_\varepsilon$  &  $e_1, \dots, e_n \stackrel{i.i.d.}{\sim} \mathbb{P}_e$  and

$$0 < \mathbb{E}[|e_1|^2] < \infty \quad \text{and} \quad 0 < \mathbb{E}[|\varepsilon_1|^{1+t}] < \infty$$

for  $t \in [0, 1)$ .

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$$\lim_{n \rightarrow \infty} \mathbb{P} \left( \phi > \frac{1}{K+1} \right) = 0.$$

# Remarks about power analysis

- $\mathbf{Z}$  is a linear model w.r.t.  $\mathbf{X}$  & all noises i.i.d. are just for **simplicity of illustration**;

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- $Z$  is a linear model w.r.t.  $X$  & all noises i.i.d. are just for **simplicity of illustration**;
- In our paper, we proved that the same conclusion still holds when  $Z$  is a nonlinear func. w.r.t.  $X$  & all noises are heteroschedastic.

# Minimax rate optimality

- We derive that the minimax lower bound rate of separation is of order  $n^{-t/(1+t)}$  for heavy-tailed distribution;  
  
⇒ matches the **pointwise** upper bound of RPT.



# Minimax rate optimality

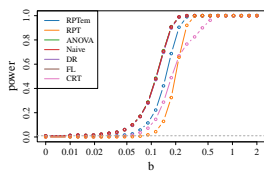
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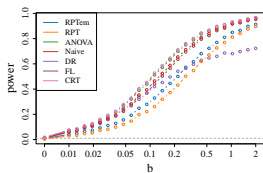
- We derive the uniform convergence rate of RPT is of  $n^{-t/(1+t)+\delta}$  for any const.  $\delta > 0$ .

⇒ RPT nearly minimax rate optimal.

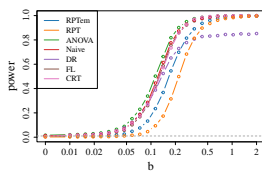
# Power curves



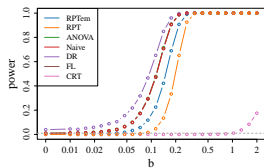
(g) Gaussian design, Gaussian noise



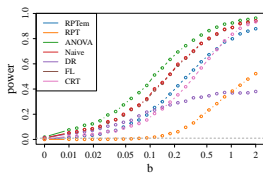
(h) Gaussian design,  $t_1$  noise



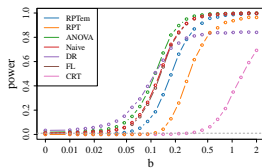
(i) Gaussian design,  $t_2$  noise



(j)  $t_1$  design, Gaussian noise



(k)  $t_1$  design,  $t_1$  noise



(l)  $t_1$  design,  $t_2$  noise

Figure:  $n = 600, p = 100$

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- **Finite population simulation:** when  $n$  is small, empirically RPT can still be **more conservative** than those **invalid** tests, especially for heavy-tailed  $\epsilon$ ;

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- **Open question:** how to develop a distribution-free & finite-population valid test with better empirical power in small sample size.

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For theoretical details and more simulation results, please see  
<https://arxiv.org/abs/2211.16182>