

# Estimation and Inference in Sparse Autoregressive Networks

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## Problem

To predict the evolution of dynamic networks, we model it by a network AR(1) process.

Given a sample of adjacency matrix  $\{X_1, \dots, X_n\}$ , our first purpose is to estimate the parameters  $(\alpha_{i,j})_{p \times p}$ ,  $(\beta_{i,j})_{p \times p}$ , and find a proper embedding into a space with lower dimension (find a simpler representation for parameters). Thus, the second purpose is to estimate  $(\theta_i, \eta_i)_{i=1}^p$ .

## Concepts

The **adjacency matrix** is one way preferred by mathematicians to represent networks. A network with  $n$  nodes can be represented by an  $n$ -by- $n$  matrix  $X$ , where node  $i$  and  $j$  are connected once  $X_{i,j} = 1$ .

$\alpha$ -**mixing coefficient** is firstly defined for two  $\sigma$ -algebra  $\mathcal{A}$  and  $\mathcal{B}$ :

$$\alpha(\mathcal{A}, \mathcal{B}) = \sup_{A \in \mathcal{A}, B \in \mathcal{B}} |P(A \cap B) - P(A)P(B)|.$$

For time series  $\{X_t\}_{t=0}^\infty$ , it is defined as:

$$\alpha_{X_t}(n) = \sup_{k \geq 1} \alpha(\mathcal{M}_k, \mathcal{G}_{k+n}),$$

where  $\mathcal{M}_j = \sigma(\{X_i, i \leq j\})$ ,  $\mathcal{G}_j = \sigma(\{X_i, i \geq j\})$

## Models

We consider an AR(1) dynamic network defined on  $p$  fixed nodes, denoted by  $\{1, \dots, p\}$ , with the  $p \times p$  adjacency matrix  $X_t = (X_{i,j}^t)$  at time  $t$  defined by

$$X_{i,j}^t = X_{i,j}^{t-1} I(\varepsilon_{i,j}^t = 0) + I(\varepsilon_{i,j}^t = 1), t \geq 1, \quad (1)$$

innovations  $\varepsilon_{i,j}^t$ ,  $1 \leq i < j \leq p$ , are independent, and

$$P(\varepsilon_{i,j}^t = 1) = \alpha_{i,j}, P(\varepsilon_{i,j}^t = -1) = \beta_{i,j}, \\ P(\varepsilon_{i,j}^t = 0) = 1 - \alpha_{i,j} - \beta_{i,j}.$$

Thus,  $\{X_t\}$  is a Markov process, with

$$P(X_{i,j}^t = 1 | X_{i,j}^{t-1} = 0) = \alpha_{i,j},$$

$$P(X_{i,j}^t = 0 | X_{i,j}^{t-1} = 1) = \beta_{i,j}.$$

In addition, assume parameters  $\alpha_{i,j}$  and  $\beta_{i,j}$  is generated from  $\{\theta_i, \eta_i\}_{i=1}^p$  by:

$$\alpha_{i,j} = \theta_i \theta_j, \quad \beta_{i,j} = \eta_i \eta_j.$$

This setting comes from the insights that connecting and breaking probability  $\alpha_{i,j}, \beta_{i,j}$  should be explained by node  $i$  and node  $j$ 's node-specific property:  $\theta_i, \eta_i$  and  $\theta_j, \eta_j$ . Here the property is in dimension 1, and the dimension could be higher, the corresponding model is called dot-product random graph.

## References

- [1] Merlevede, F., Peligrad, M., Rio, E., et al. (2009). Bernstein inequality and moderate deviations under strong mixing conditions. In *High dimensional probability V: the Luminy volume*, pages 273–292. Institute of Mathematical Statistics.
- [2] Jiang, B., Li, J., and Yao, Q. (2020). Autoregressive networks. *arXiv preprint arXiv:2010.04492*.

## Sparsity is an Issue in Network Parameter Estimation

The sparsity in networks is not like in the linear model, where we assume only a small number of all features are strong features that actually affect the response variable. Here, sparsity means the expected number of edges divided by the number of all possible edges  $\rho_p = \frac{\sum_{i,j=1}^p E[X_{i,j}]}{p(p-1)/2}$  goes to zero as  $p$  goes to infinity.

Under our setting,  $\rho_p = \frac{\sum_{i,j=1}^p E[X_{i,j}]}{p(p-1)/2} = \frac{2}{p(p-1)} \sum_{1 \leq i < j \leq p} \frac{\alpha_{i,j}}{\alpha_{i,j} + \beta_{i,j}} = \frac{2}{p(p-1)} \sum_{1 \leq i < j \leq p} \frac{1}{1 + \beta_{i,j}/\alpha_{i,j}}$ . It is clear that if  $\alpha_{i,j}$  and  $\beta_{i,j}$  are bounded away from 0 ( $\liminf_{p \rightarrow \infty} \alpha_{i,j} > 0$ ,  $\liminf_{p \rightarrow \infty} \beta_{i,j} > 0$ ), then the network is not sparse. Asymptotic results under non-sparse settings have been thoroughly investigated.

One way to understand why sparse is an issue is to treat it as signal processing:

$$X = E[X] + P$$

where  $E[X] = (\frac{\alpha_{i,j}}{\alpha_{i,j} + \beta_{i,j}})_{p \times p}$  is the expected value of the adjacency matrix, while  $X$  is the realisation (of  $p(p-1)/2$  number of Bernoulli distribution), while  $P$  satisfying  $E[P] = 0$  is the noise (or error term).

## Methods

We estimate  $\alpha$  and  $\beta$  by conditional Maximum Likelihood Estimation.

$$\hat{\alpha}_{i,j} = \frac{\sum_{t=1}^n X_{i,j}^t (1 - X_{i,j}^{t-1})}{\sum_{t=1}^n (1 - X_{i,j}^{t-1})}, \quad \hat{\beta}_{i,j} = \frac{\sum_{t=1}^n (1 - X_{i,j}^t) X_{i,j}^{t-1}}{\sum_{t=1}^n X_{i,j}^{t-1}}, \quad \hat{\pi}_{i,j} = \frac{\hat{\alpha}_{i,j}}{\hat{\alpha}_{i,j} + \hat{\beta}_{i,j}}. \quad (2)$$

Next, by using  $\hat{\alpha}$ , we aim to estimate  $\theta$ . Directly listing all equations  $\hat{\alpha}_{i,j} = \hat{\theta}_i \hat{\theta}_j$  for  $1 \leq i < j \leq p$  does not necessarily yield solutions, since  $\hat{\alpha}_{i,j}$  are noise versions of  $\alpha_{i,j}$ , therefore the matrix  $(\hat{\alpha}_{i,j})_{p \times p}$  are very likely to not be in 1 dimension. (there are  $p(p-1)/2$  number of equations, and only  $p$  number of variables)

We propose a method to solve for  $\hat{\theta}_i$ : consider summation for  $p$  number of rows:

$$\sum_{j=1, j \neq i}^p \hat{\theta}_i \hat{\theta}_j = \sum_{j=1, j \neq i}^p \hat{\alpha}_{i,j}, \quad \forall i = 1, \dots, p.$$

Now there are  $p$  number of equations and  $p$  number of variables. Although it is in the quadratic form, we prove this is a convex problem, thus having a unique solution.

Given the estimation strategy, we could derive the probability bound for these estimators.

**Lemma 1.** For  $t \geq 1$ , Define  $Y_{i,j}^t = X_{i,j}^t (1 - X_{i,j}^{t-1})$ . Set  $c_Y = \frac{1}{4}(\alpha_{i,j} + \beta_{i,j})$ , then, for any  $n \in \mathbb{N}$ ,

$$\alpha_{Y_{i,j}^t}(n) \leq \exp\{-2c_Y n\}. \quad (3)$$

**Theorem 1.** Let  $n \geq 4$ . For any  $t$  such that

$$0 < t \leq \frac{\alpha_{i,j} \beta_{i,j}}{8 \left[ \log_2 \left( \frac{n}{\alpha_{i,j} + \beta_{i,j}} \right) \right]^2 (\alpha_{i,j} + \beta_{i,j})},$$

we have the non-asymptotic bound for the Moment Generating Function of  $S_{(0,n]}$ :

$$\log \mathbb{E} \exp\{t S_{(0,n]}\} \leq 15.5 t^2 v^2 n + 1.4 n \exp\left\{-\frac{\alpha_{i,j} + \beta_{i,j}}{24t}\right\} + \frac{8 t^2 n \alpha_{i,j} \beta_{i,j}}{(\alpha_{i,j} + \beta_{i,j})^3} + \frac{1}{8}. \quad (4)$$

Furthermore, for any  $\varepsilon_{n,p} > 0$  and  $\varepsilon_{n,p} = o\left(\frac{(\alpha_{i,j} \beta_{i,j})^2}{(\alpha_{i,j} + \beta_{i,j})^4 \left[ \log_2 \left( \frac{n}{\alpha_{i,j} + \beta_{i,j}} \right) \right]^2}\right)$ , there exists a constant  $C > 0$  only depends on an upper bound of  $\alpha$ -mixing coefficient of  $\{X_{i,j}^t\}_{t=0}^\infty$ , such that the inequality below holds for all sufficiently large  $n$ .

$$\mathbb{P}\left(\left|\frac{1}{n} \sum_{t=1}^n (X_{i,j}^t - \pi_{i,j})\right| \geq \varepsilon_{n,p}\right) \leq 10 \exp\left\{-\frac{C n (\alpha_{i,j} + \beta_{i,j})^3 \varepsilon_{n,p}^2}{\alpha_{i,j} \beta_{i,j}}\right\}. \quad (5)$$

(C1) As  $n, p \rightarrow \infty$ , it holds that  $\frac{(\alpha_{i,j} + \beta_{i,j})^3}{(\alpha_{i,j} \beta_{i,j})^{3/2}} \left(\log \frac{n}{\alpha_{i,j} + \beta_{i,j}}\right)^2 \sqrt{\frac{\log p}{n(\alpha_{i,j} + \beta_{i,j})}} \rightarrow 0$ .

**Corollary 1.** Let condition (C1) hold. For any  $\kappa > 0$ , and any  $p$  there exists a constant  $C_\kappa$  only depends on  $\kappa$ , such that for all sufficiently large  $n$ ,

$$\mathbb{P}\left(\left|\frac{1}{n} \sum_{t=1}^n X_{i,j}^t - \pi_{i,j}\right| \geq C_\kappa \sqrt{\frac{\alpha_{i,j} \beta_{i,j} \log p}{n(\alpha_{i,j} + \beta_{i,j})^3}}\right) \leq p^{-\kappa}. \quad (6)$$